

Ultrasonic Blind Aid Stick for the Visually Impaired and Physically Disabled

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Abstract:*The main specific objective of this paper is to help the visually impaired people by developing and implementing solutions to social, cultural, or environmental issues. Visually impaired persons face challenges to go out independently. There are millions of visually impaired or in this world who are always in need of helping hands. For many years white cane was known to be helpful to blind person's navigation but later sensors were used to make that stick which helped the blind people. Blind people face many problems while walking on the street. The blind aid walking stick will help the blind person by providing more convenient means of life. The main aim of this paper is to help the people of blind and disable society of the world.*

Keywords: Ultrasonic sensors, Blind Aid Stick, Visually Impaired, Microcontroller.

1. Introduction

According to the statistics, there are 37 million people across the globe who are blind, over 15 million are from India. This project proposes to design and develop a blind aid stick for them for easy usage and navigation in public places. The blind stick is integrated with ultrasonic sensors [1]. This project idea first makes the use of ultrasonic sensors by generating ultrasonic waves and detects the obstacles. After detecting the obstacles, the information is then sent to microcontroller [2]. The microcontroller processes this received data and calculates whether the obstacle is close enough or not. If the detected obstacle is beyond the threshold distance the circuit does nothing. If the obstacle is close enough the microcontroller sends a signal to the buzzer. Thus, this system allows for obstacle detection by visually disabled person [3].

2. Materials and Methods

The main objective of this project is to help visually challenged people to walk without any difficulty with the use of this technology. In this present scenario, where people strive to live independently, this project proposes a blind aid stick for blind people to help them achieve independence. Since this is product will be economical and will not be bulky, one can make use of it easily.

In this stick the ultrasonic sensors placed are used to detect the obstacle. The sensors are set a threshold limit if any obstacle is found within that range it gives beep speech through speaker. The ultrasonic waves generated by the different ultrasonic sensors hits the obstacle and bounces back to detectors. The ultrasonic sensor are used for detecting the obstacles which are in front and the two infrared sensors are used to detect the obstacles on the sides. After the collection of data the calculations are done, once the distance of the obstacle is calculated then the conditions are checked. The received signal is sent to microcontroller to

operate a buzzer.

The microcontroller will read the distance of the obstacle with the help of sensors and will operate the buzzer accordingly. The buzzer would beep once for left side obstacle, twice for front obstacles and thrice for right obstacles. A vibrator can also be connected in parallel with the buzzer for vibration sensation.

3. Survey

S.Gangwar (2011) designed a smart stick for blind which can give early warning of an obstacle using Infrared (IR) sensors.

S.Chew (2012) proposed the smart white cane, called Blind spot that combines GPS technology, social networking and ultrasonic sensors to help visually impaired people to navigate public spaces.

Benjamin et al (2011) had developed a smart stick using laser sensors to detect the obstacles and down curbs.

Central Michigan University (2009) developed an electronic stick for blind people that would provide contextual information on the environment around the user. They used RFID chips which are implanted into street signs, store fronts, similar locations, and the cane reads those and feeds the information back to the user.

Mohd Helmyabd Wahab and Amirul A. Talib et al (2011) developed a cane could communicate with users through voice alert and vibration signal). Ultrasonic sensors are used to detect the obstacle in front, as the ultrasonic sensors are good in detecting obstacle in few meters range and this data would be sent in the form of voice signal.

4. Tables

Table 1: Number of people visually impaired and corresponding percentage of the global impairment by WHO Region and country

WHO Regions	Total Population (in millions)	Blindness No. in millions (percentage)	Low Vision No. in millions (percentage)	Visual Impairment No. in millions (percentage)
Afr	804.9 (11.9)	5.888 (15)	20.407 (8.3)	26.295 (9.2)
Amr	915.4 (13.6)	3.211 (8)	23.401 (9.5)	26.612 (9.3)
Emr	580.2 (8.6)	4.918 (12.5)	18.581 (7.6)	23.499 (8.2)
Eur	889.2 (13.2)	2.713 (7)	25.502 (10.4)	28.215 (9.9)
Sear (India excluded)	579.1 (8.6)	3.974 (10.1)	23.938 (9.7)	27.913 (9.8)
Wpr (China excluded)	442.3 (6.6)	2.338 (6)	12.356 (5)	14.724 (5.2)
India	1181.4 (17.5)	8.075 (20.5)	54.544 (22.2)	62.619 (21.9)
China	1344.9 (20)	8.248 (20.9)	67.264 (27.3)	75.512 (26.5)
World	6737.5 (100)	39.365 (100)	246.025 (100)	285.389 (100)

Table 2: Studies used for the global estimate of visual impairment

WHO Region	Countries with studies
African Region	Botswana, Cameroon, Eritrea, Ethiopia, Gambia, Ghana, Kenya, Mali, Nigeria, Rwanda, Uganda, United Republic of Tanzania
Region of the Americas	Argentina, Brazil, Chile, Cuba, Dominican Republic, Guatemala, Mexico, Paraguay, Peru, Venezuela
Eastern Mediterranean Region	Islamic Republic of Iran, Oman, Pakistan, Qatar
European Region	Russian Federation, Turkmenistan
South-East Asian Region	Bangladesh, Democratic Republic of Timor-Leste, India, Indonesia, Myanmar, Nepal
Western Pacific Region	Cambodia, China, Papua New Guinea, Philippines, Vietnam

Table 3: Global estimate of the number of people visually impaired by age; for all ages in parenthesis the corresponding prevalence (%)

Age (in years)	Population (millions)	Blind (millions)	Low Vision (millions)	Visually Impaired (millions)
0-14	1848.50	1.421	17.518	18.939
15-49	3548.2	5.784	74.463	80.248
50 and older	1340.80	32.16	154.043	186.203
all ages	6737.50	39.365	246.024	285.389

5. Results

All the studies which have been reviewed shows that, there are a numerous of techniques for making a blind-aid walking stick for blind people. The advantage of the system is that it can prove to be a very low cost solution to millions of blind person worldwide. This could also be considered an easy way of giving the blind a sense of vision.

6. Future Scope

The system can be addtioanlly fitted with a GPS MODULE and the location can be sent to relative of the blind person. We can also make use of a vibrator for deaf people. It can be enhanced and can be optimised in size by using VLSI technology to design the PCB unit. This would make the device more compact. Additionally, a wall following function can be added so that the disabled person can walk straight in the corridor or in any place.

7. Conclusion

It works as a steering device for the blind people. This project mainly focuses to provide a good navigation system for the visually impaired people of the world. This system can be used to navigate by everyone, not only visually defective under certain conditions, like misty mornings with low visibility. Some winter mornings are cloudy. Where the visibility is very little, then this system can be used. This system can also be used by patient’s adversity with various eye aches like cataract, Exophthalmia, post eye functioning situations and others. This system can be adapted into a more sophisticated version of itself by using a high concentration ultrasonic effect to be used as a navigation system for geological analysis. Hence this system has a good future scope.

8. Acknowledgment

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9. Declaration

The author(s) declare(s) that there is no conflict of interest.

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