

Comparative Study of Spectrum Sensing Techniques Applied in Cognitive Radio Technology

Santhadevi Perumalsamy¹, Hemalatha Kanagaraj²

¹M.Phil (CS) Scholar, Department of Computer Applications, Sri Jayendra Saraswathy Maha Vidyalaya College of Arts and Science, Coimbatore, India

²Assistant Professor, Department of Computer Applications, Sri Jayendra Saraswathy Maha Vidyalaya College of Arts and Science, Coimbatore

Abstract: Cognitive radio is widely expected to be the upcoming research topic in wireless communications sector. Detecting the presence of primary users in a licensed spectrum is achieved through the technique called spectrum sensing. In this paper spectrum two types of spectrum sensing techniques namely energy detection and matched filter techniques are reviewed.

Keywords: Cognitive Radio (CR), Dynamic Spectrum Access (DSA), Primary User (PU), Secondary User (SU), Software Defined Radio (SDR)

1. Introduction

In our day to day life the existence of electromagnetic radio spectrum are found in scarce and is getting utilized frequently.

It is additionally discovered that the apportioned range are underutilized because of its static allocation mechanism which is the traditional methodology of spectrum management and is exceptionally unyielding to work in a specific recurrence band. Furthermore, with a large portion of the helpful radio range previously designated, it is hard to discover empty groups or to improve existing ones. To beat this circumstance, we have to concoct a methods for enhanced usage of the range making openings and i.e., Dynamic range get to. The issue of range underutilization in remote correspondence can be settled bitterly utilizing Cognitive Radio (CR) innovation. Subjective radios are planned with the end goal to give profoundly dependable correspondence to all clients of the system, wherever and at whatever point required and to encourage successful use of the radio range. Cognitive radio: It is a radio that can change its transmitter parameters dependent on collaboration with condition in which it works. Cognitive radio incorporates spectrum detecting/sensing, spectrum management, and spectrum sharing finally spectrum portability.

- Spectrum sensing: Detecting unused spectrum and sharing the spectrum without harmful interference with other users.
- Spectrum management: Capturing the best available spectrum to meet user communication requirements.
- Spectrum mobility: Maintaining seamless communication requirements during the transition to better spectrum.
- Spectrum sharing: Providing the fair spectrum scheduling method among coexisting xG users.

2. Cognitive Radios

Cognitive radios is another term in remote correspondence innovation which interfaces with continuous condition to progressively adjust its working parameters, for example, transmit control, bearer recurrence, balance to adapt itself

with the earth at whatever point there is a measurable change in the approaching radio recurrence with the sole reason to exploit the accessible range without making obstruction essential clients.

Cognitive radio incorporates astute location by a handset, which watches what correspondence diverts are being used and which are not, and takes an immediate arrangement of moving to empty channels while staying away from possessed ones. This advances the utilization of accessible Radio-Recurrence (RF) range while limiting impedance to different clients. The most essential frame, CR is a cross breed innovation including Software Defined Radio (SDR) It performs allotment recognizable proof and approval of its client and changes yield power and tweak qualities it is to be noticed that SDR can't reconfigure independent from anyone else while CR can perform

Re-configurability. The Government Interchanges Commission (FCC) decided in November 2008 that unused parts of the RF range (known as blank areas) be made accessible for open utilize. Void area gadgets must incorporate advances to avoid obstruction, for example, range detecting and movement abilities [3-5].

The thought for CR was created by Joseph Mitola at the Safeguard Propelled Exploration Tasks Organization (DARPA) in the Assembled States. Full cognitive radio is once in a while known as "Mitola Radio." software. The CR is seen as the key empowering innovation for future portable remote administrations anyplace, whenever and with any gadget

3. Spectrum Sensing

Spectrum detecting is the technique to quantify, range of spectrum and know about the parameters identified with the radio channel attributes, accessibility of spectrum and transmit power, obstruction and commotion,

radio's working condition, client prerequisites and applications, accessible systems (frameworks) and hubs, neighborhood strategies and other working confinements. It is done crosswise over Recurrence, Time, Land Space, Code and Stage. Spectrum detecting is the plain undertaking whereupon the whole task of intellectual radio rests. To permit dependable activity of subjective radios, we should have the capacity to distinguish correctly the spectrum holes at the connection level (that is sure recurrence groups are not utilized for transmission at specific occasions), which gives spectrum detecting a basic job. By and by, the unlicensed users, likewise called secondary users (SUs), need to persistently screen the exercises of the authorized users, additionally called Primary Users (PUs), to discover the spectrum holes (SHs), or, in other words the spectrum groups that can be utilized by the SUs without meddling with the PUs. This system is called spectrum detecting. There are two kinds of SHs, specifically worldly and spatial SHs, separately. A worldly SH shows up when there is no PU transmission amid a specific era and the SUs can utilize the spectrum for transmission. A spatial SH shows up when the PU transmission is inside a zone and the SUs can utilize the spectrum outside that territory. To decide the nearness or nonattendance of the PU transmission, diverse spectrum detecting methods have been utilized, for example, coordinated separating location, vitality discovery, and highlight identification. Be that as it may, the execution of spectrum detecting is constrained by commotion vulnerability, multipath blurring, and shadowing, which are the basic attributes of remote channels.

3.1 Principle of spectrum sensing

Fig. 1 shows the principle of spectrum sensing. In the fig. the PU transmitter is sending data to the PU receiver in a licensed spectrum band while a pair of SUs intends to access the spectrum. To protect the PU transmission, the SU transmitter needs to perform spectrum sensing to detect whether there is a PU receiver in the coverage of the SU transmitter.

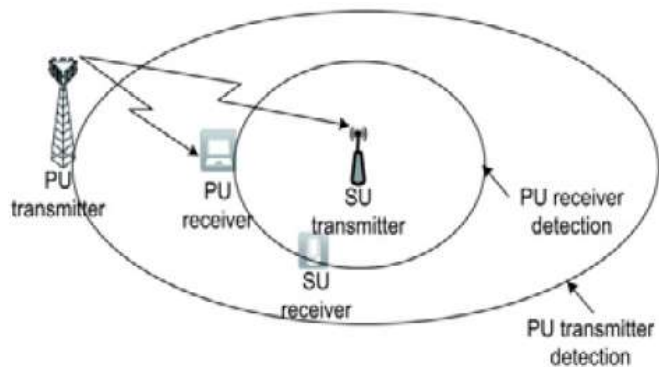


Figure 1: Transmitter and Receiver Architecture

3.2. Spectrum Sensing Detection Methods

Features that cognitive radios can incorporate to enable a more efficient and flexible usage of the spectrum.

i. Frequency Agility

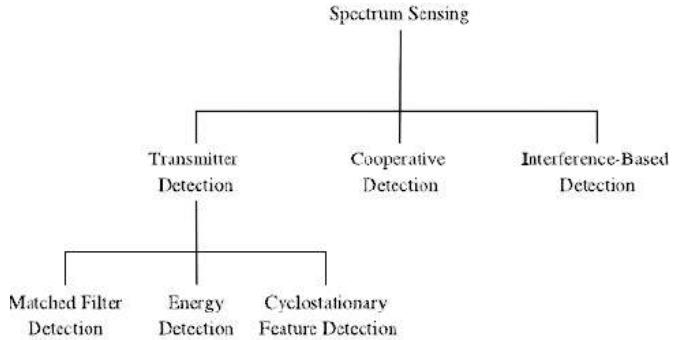
The cognitive radio is able to change its operating frequency for its adaptation to the environment.

ii. Dynamic Frequency Selection

The cognitive radio senses signals from nearby transmitters to choose an optimal environment to work in.

iii. Adaptive Modulation

The transmission characteristics and waveforms can be reconfigured to exploit all opportunities for the usage of spectrum in an efficient way.



iv. Transmit Power Control

The transmission power is adapted to full power limits when necessary on the one hand and to lower levels on the other hand to allow greater sharing of spectrum.

4. Techniques followed for a Primary Transmitter Detection

(i) Energy Detection

It is a non-coherent detection strategy. Under this method the essential flag based on the sensed energy is detected. It is easy to actualize and furthermore while utilizing energy detection we don't require the earlier knowledge of essential flag. Additionally Energy Detection (ED) is the most well known sensing strategy in cooperative sensing Spot table titles over the tables.

In this strategy, flag is passed through band pass filter of the bandwidth W and is integrated after some time interim. The yield from the integrator square is then compared to a predefined edge.

The correlation of info flag and limit flag is used to find the presence or nonattendance of the essential client. The edge esteem can set to be fixed or variable based on the channel conditions. We additionally call Energy detection system as Visually impaired Flag DETECTION since it overlooks the structure of the flag and gauges the nearness of the flag by contrasting the energy received and a known edge derived from the measurements of the commotion. While examining we reduce flag detection to a basic Recognizable proof issue, as a speculation (hypothesis) test

$$y(k) = n(k) - H_0$$

$$y(k) = h * s(k) + n(k) - H1$$

Where y (k) is the sample to be analyzed at each instant k n (k) is the noise of variance σ^2 Let y (k) be a sequence of received samples k E {1, 2,...N} at the signal detector, then a decision rule can be stated as,

$$H_0 \dots \dots \text{if } \epsilon < \nu$$

$$H_1 \dots \dots \text{if } \varepsilon > \nu$$

Where $\varepsilon = E y(k)^2$ the estimated energy of the received signal and ν is chosen to be the noise variance σ^2 .

Disadvantages associated to ED are as follows;

- 1) High sensing time taken to achieve a given probability.
- 2) Detection performance is subject to the uncertainty of noise power.
- 3) Using Energy Detection technique it is difficult to distinguish primary signals from the CR user signals.
- 4) CR users need to be tightly synchronized and refrained from the transmissions during an interval called Quiet Period in cooperative sensing.
- 5) ED not suitable to detect spread spectrum signals.

(ii) Matched Filter Detection:

A matched filter (MF) is a direct filter intended to amplify the yield signal to clamor proportion for a given info signal. In matched filter detection the secondary user has from the earlier knowledge of primary user signal is required Matched filter activity is equal to connection in which the obscure signal is convoluted with the filter whose drive reaction is the mirror and time moved variant of a reference signal. The task of matched filter detection is communicated as follows;

Where ‘x’ is the unknown signal (vector) and is convoluted with the ‘h’, the impulse response of matched filter that is matched to the reference signal for maximizing the SNR. is known to the cognitive users.

Advantages	Disadvantages
Matched filter detection needs less detection time because it requires only $O(1/\text{SNR})$ samples to meet a given probability of detection constraint.	Matched filter detection requires a prior knowledge of every primary signal.
When the information of the primary user signal is known to the cognitive radio user, matched filter detection is optimal detection in stationery Gaussian noise	For Matched filter detection CR would need a dedicated receiver for every type of primary user.

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Author Profile



Mrs. Santhadevi Perumalsamy completed B.Sc (CS), MCA, during 2006 and 2009, and started her career as a technocrat designated as Junior Software Engineer at RVS infotech Coimbatore, later she inculcated her passion towards education sector then completed her B.Ed in Computer Science (2012), at present pursuing her M.Phil in Computer Science. From 2012 Onwards she stepped into Pre-University level to tertiary level and continued lecturing the students in various capacities in India, Malawi & Ghana.



Mrs. Hemalatha Kanagaraj has completed MCA., M.Phil., heading the Department of Computer Application in Sri Jayendra Saraswathy Maha Vidyalaya College of Arts and Science, Coimbatore. She has more than 15 years of experience in lecturing field, she has gained a tremendous experience while pursuing her M.Phil research work. She has contributed her knowledge in national level publication proceedings and partaken in technical symposiums, Conferences and workshops for enriching her knowledge to perform an excellent teaching, learning practice.