

An Optimized Task Scheduling Algorithm and Maintaining the Load in Cloud Environment

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Abstract: *Cloud provides convenient and on demand network access for computing resources available over internet. Individuals and organizations can access the software and hardware such as network, storage, server and applications which are located remotely easily with the help of Cloud Service. The tasks/jobs submitted to this cloud environment needs to be executed on time using the resources available so as to achieve proper resource utilization, efficiency and lesser makespan which in turn requires efficient task scheduling algorithm for proper task allocation. In this paper, we have introduced an Optimized Task Scheduling Algorithm which adapts the advantages of various other existing algorithms according to the situation while considering the distribution and scalability characteristics of cloud resources.*

Keywords: Cloud Computing, Makespan, Minimum/ Maximum Execution Time, Minimum/Maximum Completion Time, Load Balancing

1. Introduction

Now days a wide variety of computer ideas has been introduced i.e., Cloud supplies the user with sufficient and on-demanding contact of set-up for N no of computing resources available on the Internet. Cloud environment which has a widely scattered computing media that holds a huge content of virtualized computing sources that are near to the discrete or an institute. The actual motivation behind the implementation of CC is to supply a most promising worth able packages which is little bit stimulating. Scheduling of engagement in activity application and maintaining surfeit is just what was ordered a main am a source of in dwarf environment. This gave a pink slip be achieved by adopting proficient task scheduling algorithm. By over parameters a well-known as throughput, resource employment, charge, computational has a head start, pride of place, attitude, baud rate, resource availability and many preferably, time management algorithms are implemented. By over parameters a well-known as throughput, resource employment, charge, computational has a head start, pride of place, attitude, baud rate, resource availability and many preferably, Scheduling algorithms are implemented. In decision to provide has a jump on Quality of Service (QoS), we prefer to bring about an capable hardship scheduling algorithm which maintains a valuable balance during resource hard pull to train efficiency, lesser derive span, concurrent task scheduling, having to do with resource hard pull and management. This complimentary is like the point of departure of latest course for scheduling task completely the at hand staple mutually analogy from the prompt one. Our intensify is to hast a portion of the tasks around the resources in an know ins and outs manner to move up in the world lesser derive span as compare with other urgent algorithms.

This paper is regarding the introduction of latest technique for scheduling task over the available resources with comparison from the existing one. My focus is to distribute

the tasks over the resources in an appropriate manner to achieve lesser make span as compare with other existing algorithms.

Scheduling of tasks and allocation of resources are the important features of the cloud environment which directly affect the performance of a system. In order to achieve high throughput, various task scheduling algorithms have been introduced by the researchers for scheduling and scaling of resources. The adaption of the appropriate algorithm decides the performance of the system..

2. Methodology

- Job scheduling is done by adapting the existing cheduling algorithms. These algorithms when schedule tasks follow the same principal in each situation sometimes leading to increase in makespan of the processes.
- Time over all available resource is calculated for all processes; it tells about the total time taken by individual resource to execute all tasks.
- The task which needs to be migrated from one Resource to another so that makespan can be reduced.

A. Existing Algorithm

In cloud computing, all tasks have different features from each other. The main purpose of scheduling algorithm is fairly allocation of task over available resources and evenly distribution of workload as much as possible. To solve the problem of scheduling of tasks over available resources, numbers of algorithms have been introduced by researchers.

But many of those algorithms are not applicable in large scale distributed systems such as cloud environment or grid environment due to high communication cost. In this section, we will have a look over some existing. Scheduling algorithms which were introduced in order to serve qualitatively to the users. Some of them are:

i. Min-Min

It is a heuristic algorithm that starts by the whole of a apply of generally unmapped [14][1] tasks and employment by willingly finding the least possible expected anticipate of all tasks in meta-task. The hardship having the least possible expected closure time is occupied and situated the exact resource[1]. This hike is iterated until Meta-task is not empty. Here, carrying a lot of weight task has to warble for the end of the line of smaller ones.

ii. Max-Min

This is routinely used algorithm in abstracted environment which is gradually similar to the Min-min algorithm[14][1]. For starting this algorithm, expected cessation anticipates of each strain as using the accessible resource is calculated. A difficulty which has completely maximum closing time is scheduled far and wide a resource with completely minimum death warrants time. This race is regular until meta-task is not empty. Here, the waiting time of larger difficulty is reduced.

iii. RASA

RASA stands for “Resource Aware Scheduling Algorithm”. RASA[15] is as a matter of course used algorithm in distributed environment which is gradually similar to the Min-min algorithm. For starting this algorithm, expected closing pioneer of each load as via the accessible resource is calculated. A responsibility which has completely maximum cessation time is scheduled round a resource with far and wide minimum capital punishment time. This stride is extended until meta-task is not empty. Here, the waiting time of larger difficulty is reduced.

iv. Improved Max-Min

The Max Min algorithm [11] schedules the duty as using the over maximum capital punishment time overall the resource that provides far and wide minimum cessation time. This algorithm supports fill balancing of accessible resources and allows concurrent death warrant of the submitted tasks. Total makespan is calculated everywhere larger responsibility execution.

v. Enhanced Max-Min

This algorithm instructed a modified Max-min algorithm [8]. This algorithm selects the difficulty mutually the respectable or nearest to sufficient execution anticipates instead of selecting largest tax for execution. This selected task is before scheduled during the resource by the whole of minimum closing time. This algorithm reduces the completely makespan and besides balances pall across resources.

B. Proposed Algorithm

- a) Algorithm which adapts the advantages of various other existing algorithms according to the situation while considering the distribution and scalability characteristics of cloud resources.
- b) Have introduced an Optimized Task Scheduling Algorithm which adapts the advantages of various other existing algorithms according to the situation while considering the distribution and scalability characteristics of cloud resources.

- c) The proposed system uses
 - 1. Task scheduling in cloud computing.
 - 2. Makespan
- d) Uses:
 - Lesser makespan
 - Maintaining Load Balance
 - Less delivery time

3. Result

In the below system design Client gives N no. of file to the cloud operated by the Coordinator. Coordinator can receive the N no. of task as T1, T2, T3, T4, T5,Tn. Then the Coordinator can group the task based on the length of the task like group1 and group2 and next schedule the task is sorting each group by length as group1 and group2. After scheduling resource allocation is done by the Coordinator. The resources can be retrieved from the VM1 and VM2 the evaluation will be done in cloud by using constraints such as physical memory and CPU usage after evaluating these resource the maximum demand task group submitted to maximum capacity VM and the minimum demand task group submitted to minimum capacity VM respectively. Finally it will evaluate the VM efficiency these operation can be diagrammatically as shown in above figure1

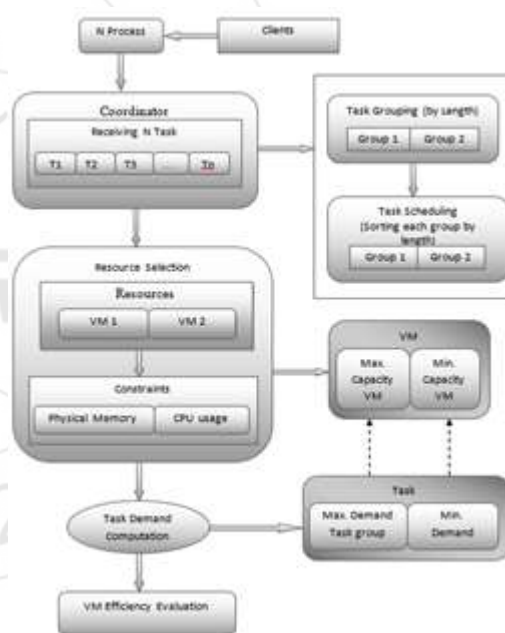


Figure 1: System Design

4. Experimentation

Example and Analysis

Let us assume a meta-task M_v with five tasks T1, T2, T3, T4 and T5 and two resources R1 and R2. The processing speed and the bandwidth of communication links for each resource is shown in Table 1, whereas, Instruction Volume and Data Volume for each task is depicted in Table 2. The expected execution time of each task over all available resource is calculated. The results for the same are shown in Table 3.

Table 1: Resource Specification

Resource	Processing Speed (MIPS)	Bandwidth (MBPS)
R1	100	130
R2	800	60

Table 2: Meta Task Specification

Task	Instruction Volume (MI)	Data Volume (Mb)
T1	1400	95
T2	1600	66
T3	1200	47
T4	800	53
T5	1000	97

Table 3: Execution time of Tasks via Resource

Task	Resources	
T1	14	1.75
T2	16	2
T3	12	1.5
T4	8	1
T5	10	1.25



- * ET = Execution Time
- * TET = Total Execution Time
- * MET = Minimum Execution Time
- * SR = Slowest Resource
- * FR = Fastest Resource

Figure 2: Optimized Task Scheduling Algorithm (Flowchart)

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1. for all submitted tasks  $T_i$  in meta-task  $M_v$ 
2. for all resources,  $R_j$ 
3. Compute  $E_{ij}$ 
4.  $Y_{ij} = \sum E_{ij}$ 
5. While meta-task is not empty
6. for all tasks over fastest resource  $r_i$ 
7.  $Z_i = Y_i - E_i$ 
8. for all task over slowest resource  $r_j$ 
9.  $A_j = E_j > Z_j$ 
10.  $s_1 = \min(A_j)$  // first optimized value
11. do if  $s_1 \geq Y_i$ 
12.  $s_2 = \min(E_j)$  // first MET over SR
13.  $s_3 = \text{second min}(E_j)$  // second MET over SR
14. do if  $s_2 \geq Y_i$ 
15. Execute RASA
16. else if  $s_3 \geq Y_i$ 
17. Schedule  $\min(E_j)$  over  $r_j$ 
18. Execute RASA for rest tasks over  $r_i$ 
19. else schedule  $\min(E_j)$  over  $r_j$ 
20. else
21.  $s_4 = Y_j - s_1$ 
22. do if  $s_1 \geq s_4$ 
23. Schedule  $s_1(E_i)$  over  $r_i$ 
24. else if  $s_1 = \max(E_j)$ 
25. Schedule second  $\max(E_j)$  over  $r_j$ 
26. else schedule  $s_1(E_j)$  over  $r_j$ 
27. Execute Min-Min for rest task
    
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- * T_i : Tasks in meta-task M_v
- * r_i : Fastest Resource
- * r_j : Slowest Resource
- * E_{ij} : Execution Time of a task with respect to each resource
- * Y_{ij} : Total Execution Time over Fastest Resource
- * Z_i : New calculated Execution Time over FR
- * A_i : Execution Time over SR in different queue
- * $\min(E_i)$, $\max(E_i)$: Minimum and Maximum ET over FR
- * $\min(E_j)$, $\max(E_j)$: Minimum and Maximum ET over SR

Fig3. Optimized Task Scheduling Algorithm (Pseudo code)

Time Evaluation

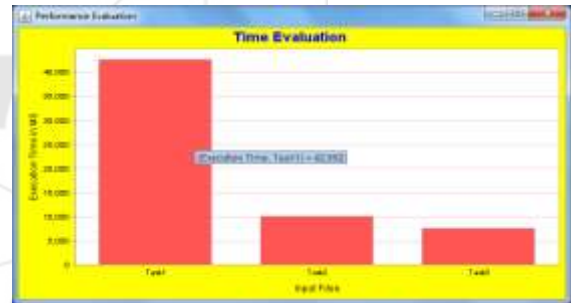


Figure 4: Time Evaluation

Memory Evaluation

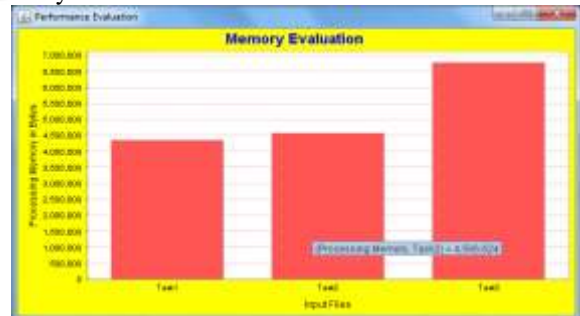


Figure 5: Memory Evaluation

Initial RAM Usage

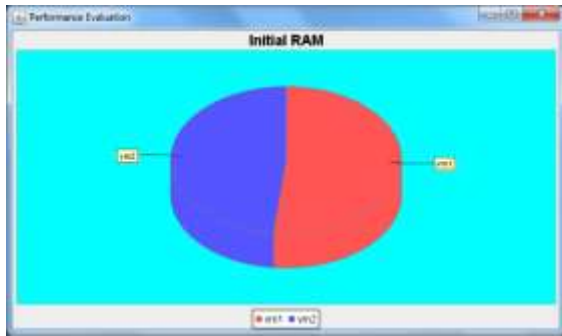


Figure 6: Initial RAM Usage

Initial CPU usage

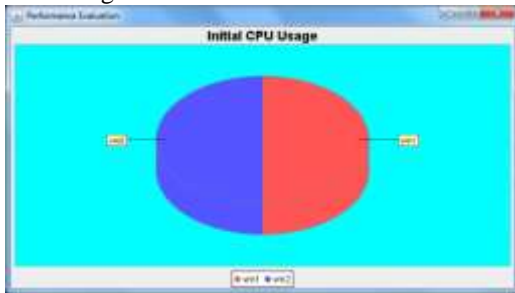


Figure 7: Initial CPU usage

RAM usage after allocation

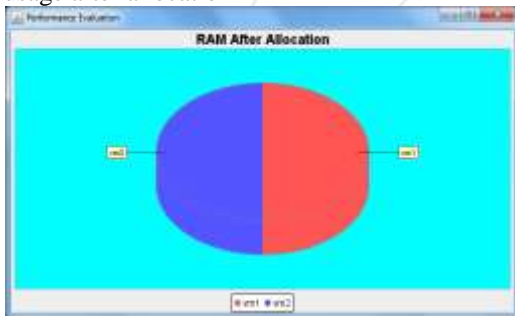


Figure 8: RAM usage after allocation

CPU usage after allocation

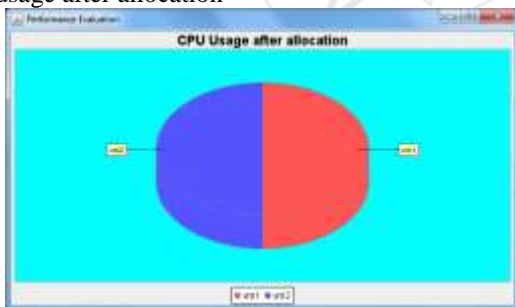


Figure 9: CPU usage after allocation

5. Conclusion

It is observed that the proposed algorithm improves resource utilization and completion time of tasks as compared to Sequential Assignment. The turnaround time of each job is minimized individually to minimize the average turnaround time. The results improve with the increase in task count. Processing power of virtual machines are computed using CPU and RAM properties. Hence, I achieved maximum utility of resources by allocating the maximum demand task group to maximum capacity virtual machine in cloud.

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