









- [3] Anderson J., "An Ensemble Adjustment Kalman Filter for Data Assimilation," *Monthly Weather Review*, vol. 129, no. 12, pp. 2884-2903, 2001.
- [4] Quan H. W., Peng, D. L., Xue, A. K. Target tracking using ESM with bearing and Doppler frequency measurements. *Opto-Electronic Engineering*, 2011, 38(3): 9-13.
- [5] A. Doucet, N. de Freitas, and N. Gordon, *Sequential Monte Carlo Methods in Practice*, New York: Springer Publishing, 2001.
- [6] Aguiar, A. and Hespanha, J., 2006. Minimum-energy state estimation for systems with perspective outputs. *IEEE Transactions on Automatic Control*, 51, 2 (2006), 226–241
- [7] Huang, X. Y., Peng, D. L. A VSMM Algorithm based on Unscented Digraph Switch for Maneuvering Target Tracking [J]. *OptoElectronic Engineering*, 2010, 37(12): 30-34.
- [8] X. R. Li and V. P. Jilkov, "Survey of maneuvering target tracking-part I: dynamic models," *IEEE Transactions on AES*, 39(4): 1333-1364, October 2003
- [9] Dang V., "An Adaptive Kalman Filter for Radar Tracking Application," in *Proceedings of the Microwaves, Radar and Remote Sensing, Ukraine*, pp. 261-264, 2008.
- [10] Q. Fang, F. Zhao, and L. Guibas, "Lightweight sensing and communication protocols for target enumeration and aggregation,"
- [11] T. Yoo and et. al. Gain-scheduled complementary Filter design for a mems based attitude and heading reference system. *Sensors*, 11:38163830, 2011.
- [12] RAO B. S., and DURRANT-WHYTE H. F., (September 1991). "Fully decentralized algorithm for multisensor Kalman filtering," *IEE PROCEEDINGS-D*, Vol. 138, No. 5, pp. 413-420.
- [13] He C., Quijano J., and Zurk L., "Enhanced Kalman Filter Algorithm using the Invariance Principle," *IEEE Journal of Oceanic Engineering*, vol. 34, no. 4, pp. 575-585, 2009