







**Table 5:** Table Representation of the Proposed Algorithm for Example 4.

N	Edge	cost	Kruskal step1 Cost = 0*10 = 0	Kruskal step2 Cost = 0+1*20 = 20	Kruskal step3 Cost = 20+2*8 = 36	Kruskal step4 Cost = 36+2*42 = 120	Kruskal step5 Cost = 120+3*5 = 135	Kruskal step6 Cost = 135+5*8 = 175	Kruskal step 7 Cost = 175+16*17 = 447
1	S <sub>1</sub> D <sub>5</sub>	0	X	X	X	X	X	X	X
2	S <sub>2</sub> D <sub>5</sub>	0	X	X	X	X	X	X	X
3	S <sub>3</sub> D <sub>5</sub>	0	X	X	X	X	X	X	X
4	S <sub>2</sub> D <sub>1</sub>	1	S <sub>2</sub> D <sub>1</sub>	1	X	X	X	X	X
5	S <sub>1</sub> D <sub>4</sub>	2	S <sub>1</sub> D <sub>4</sub>	2	S <sub>1</sub> D <sub>4</sub>	2	X	X	X
6	S <sub>3</sub> D <sub>3</sub>	2	S <sub>3</sub> D <sub>3</sub>	2	S <sub>3</sub> D <sub>3</sub>	2	X	X	X
7	S <sub>1</sub> D <sub>1</sub>	3	S <sub>1</sub> D <sub>1</sub>	3	S <sub>1</sub> D <sub>1</sub>	3	S <sub>1</sub> D <sub>1</sub>	3	X
8	S <sub>2</sub> D <sub>3</sub>	3	S <sub>2</sub> D <sub>3</sub>	3	X	X	X	X	X
9	S <sub>3</sub> D <sub>1</sub>	4	S <sub>3</sub> D <sub>1</sub>	4	S <sub>3</sub> D <sub>1</sub>	4	S <sub>3</sub> D <sub>1</sub>	4	X
10	S <sub>3</sub> D <sub>2</sub>	5	S <sub>3</sub> D <sub>2</sub>	5	S <sub>3</sub> D <sub>2</sub>	5	S <sub>3</sub> D <sub>2</sub>	5	X
11	S <sub>3</sub> D <sub>4</sub>	5	S <sub>3</sub> D <sub>4</sub>	5	S <sub>3</sub> D <sub>4</sub>	5	X	X	X
12	S <sub>1</sub> D <sub>4</sub>	8	S <sub>1</sub> D <sub>4</sub>	8	X	X	X	X	X
13	S <sub>1</sub> D <sub>3</sub>	9	S <sub>1</sub> D <sub>3</sub>	9	S <sub>1</sub> D <sub>3</sub>	9	X	X	X
14	S <sub>1</sub> D <sub>2</sub>	9	S <sub>1</sub> D <sub>2</sub>	9	X	X	X	X	X
15	S <sub>1</sub> D <sub>2</sub>	16	S <sub>1</sub> D <sub>2</sub>	16	S <sub>1</sub> D <sub>2</sub>	16	S <sub>1</sub> D <sub>2</sub>	16	X

#### 4. Conclusion

The proposed algorithm for finding the minimum feasible solution for the transportation problem is based mainly on using Kruskal's algorithm for finding out the MST with some modification. Four different examples representing different transportation problem cases were taken into account to study the correctness and expandability of the proposed algorithm. From the results given in figures 2-5 and tables 2-5, it is clear that the proposed algorithm can be used in different transportation models and gives faster convergence criteria since it is based mainly on the reduction of the number of vertices and edges after each iteration since the time complexity of such algorithms is highly related to E(number of edges) and V (number of vertices)

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