

$$BND(C) = \left\{ x \in U / 0 < \Pr\left(\frac{C}{[x]}\right) < 1 \right\}$$

$$NEG(C) = \left\{ x \in U / \Pr\left(\frac{C}{[x]}\right) = 0 \right\}$$

In 2009, Greco et.al [3] discussed the parameterized roughest model by generalizing the above said definitions. In this model, two thresholds namely α and β are used to define the probabilistic regions and the positive, boundary and negative regions are modified as follows:

$$POS_{(\alpha,\beta)}(C) = \left\{ x \in U / \Pr\left(\frac{C}{[x]}\right) \geq \alpha \right\}$$

$$BND_{(\alpha,\beta)}(C) = \left\{ x \in U / \beta < \Pr\left(\frac{C}{[x]}\right) < \alpha \right\}$$

$$NEG_{(\alpha,\beta)}(C) = \left\{ x \in U / \Pr\left(\frac{C}{[x]}\right) \leq \beta \right\}$$

These Probabilistic regions will lead three way decisions namely acceptance, deferment and rejection respectively for any object x in U . But, however, in several cases, it is easy to compute the probability of the existence of a category $[x]$ for a given concept C using $\Pr\left(\frac{[x]}{C}\right) = \frac{|[x] \cap C|}{|C|}$

Hence as in [], by Baye's Theorem, the Positive, Boundary and Negative Regions are given by

$$POS_{(\alpha',\beta')}^B(C) = \left\{ x \in U / \log \frac{\Pr([x]/C)}{\Pr([x]/C^c)} \geq \alpha' \right\}$$

$$BND_{(\alpha',\beta')}^B(C) = \left\{ x \in U / \beta' < \log \frac{\Pr([x]/C)}{\Pr([x]/C^c)} < \alpha' \right\}$$

$$NEG_{(\alpha',\beta')}^B(C) = \left\{ x \in U / \log \frac{\Pr([x]/C)}{\Pr([x]/C^c)} \leq \beta' \right\}$$

where $\alpha' = \log \frac{\Pr(C^c)}{\Pr(C)} + \log \frac{\alpha}{1-\alpha}$

and $\beta' = \log \frac{\Pr(C^c)}{\Pr(C)} + \log \frac{\beta}{1-\beta}$

Now, we shall discuss the conventional approach on dealing the fuzzy sets to approximate under rough computing, which was discussed in [1]

3. Analysis of Fuzzy Set Using a Threshold

Consider a set D , called **R-domain** [1], satisfying the following properties:

- $D \subset (0,1)$
- If a fuzzy concept C is under computation, eliminate the values $\mu_C(x)$ and $\mu_C^c(x) \forall x \in U$ from the domain D , if they exist.
- After the computation using C , the values removed in (b) may be included in D provided A must not involve in further computation

Consider the universe of discourse $U = \{x_1, x_2, \dots, x_n\}$. Let $\alpha, \alpha_1, \alpha_2, \beta$ be the thresholds assume one of the values from the domain D , where D is constructed using the fuzzy concepts A and B . For a given threshold α and a fuzzy set A ,

the Strong α -Cut is given by $A[\alpha] = \{x \in U / \mu_A(x) > \alpha\}$. The union and intersection of fuzzy sets [10] are by the maximum and minimum of corresponding membership values respectively.

In 1972, Zadeh[9] introduced the concept of hedges. In fuzzy logic, in order to improve the efficiency of fuzziness, the concept of concentration and dilation were introduced by him.

For example, for the linguistic variable 'low' with the membership function α , the hedges 'very' and 'very very' emphasis the efficiency of the variable with the corresponding membership values α^2 and α^4 . They are called **concentration**, whereas the hedges 'slightly' and 'more slightly' dilutes the efficiency of the linguistic variables with the membership values with the corresponding membership values $\alpha^{1/2}$ and $\alpha^{1/4}$. They are called **dilation**.

Using the definitions of fuzzy sets mentioned above, the following properties were derived in [1].

- $A[\alpha_1] \cup A[\alpha_2] = A[\alpha]$ where $\alpha = \min(\alpha_1, \alpha_2)$
- $A[\alpha_1] \cap A[\alpha_2] = A[\alpha]$ where $\alpha = \max(\alpha_1, \alpha_2)$
- $(A \cup B)[\alpha] = A[\alpha] \cup B[\alpha]$
- $(A \cap B)[\alpha] = A[\alpha] \cap B[\alpha]$
- $A^c[\alpha] = A[1-\alpha]^c$
- $(A \cup B)^c[\alpha] = A^c[\alpha] \cap B^c[\alpha]$
- $(A \cap B)^c[\alpha] = A^c[\alpha] \cup B^c[\alpha]$

Using the mathematical tool derived as above, in [1], rough set approach on fuzzy sets using a threshold is introduced as discussed below.

3.1 Rough Approximations on fuzzy sets using α

Let Ψ be any partition of U , say $\{B_1, B_2, \dots, B_t\}$. For the given fuzzy concept, the lower and upper approximations with respect to α can be defined as ${}_\alpha C = \underline{(C[\alpha])}$ and ${}^\alpha C = \overline{(C[\alpha])}$ respectively.

3.1.1 Propositions

Here, by using the properties of rough sets, the following propositions [] can be obtained.

- ${}^\alpha(A \cup B) = {}^\alpha A \cup {}^\alpha B$
- ${}_\alpha(A \cap B) = {}_\alpha A \cap {}_\alpha B$
- ${}_\alpha(A \cup B) \supseteq {}_\alpha A \cup {}_\alpha B$
- ${}^\alpha(A \cap B) \subseteq {}^\alpha A \cap {}^\alpha B$
- ${}^\alpha(A^c) = ({}_{1-\alpha} A)^c$
- ${}_\alpha(A^c) = ({}^{1-\alpha} A)^c$

Now, we shall hybridize the concepts dealt in the above two sections which gives the approach of dealing a fuzzy concepts under Naïve Bayesian Probabilistic Rough Sets.

4. Naïve Bayesian Probabilistic Rough Sets Model for A Fuzzy Concept

Since, in the above both sections, the same threshold α has been used, for different purposes, to make the homogeneity,

in this paper, we replace the threshold α to obtain a Strong Cut on fuzzy sets with δ .

Hence, for a given fuzzy concept F with the threshold δ , the probabilistic positive, boundary and negative regions are respectively defined on the approximation space U/E as

$$POS_{\delta}(F) = \left\{ x \in U / \Pr \left(\frac{F[\delta]}{[x]} = 1 \right) \right\}$$

$$BND_{\delta}(F) = \left\{ x \in U / 0 < \Pr \left(\frac{F[\delta]}{[x]} < 1 \right) \right\}$$

$$NEG_{\delta}(F) = \left\{ x \in U / \Pr \left(\frac{F[\delta]}{[x]} = 0 \right) \right\}$$

For given parameters α and β , the regions of the parameterized rough sets model are given by

$$POS_{(\alpha, \beta, \delta)}(F) = \left\{ x \in U / \Pr \left(\frac{F[\delta]}{[x]} \geq \alpha \right) \right\}$$

$$BND_{(\alpha, \beta, \delta)}(F) = \left\{ x \in U / \beta < \Pr \left(\frac{F[\delta]}{[x]} < \alpha \right) \right\}$$

$$NEG_{(\alpha, \beta, \delta)}(F) = \left\{ x \in U / \Pr \left(\frac{F[\delta]}{[x]} \leq \beta \right) \right\}$$

and the Regions of Naïve Bayesian Rough Sets Model are given by

$$POS_{(\alpha', \beta', \delta)}^B(F) = \left\{ x \in U / \log \frac{\Pr([x]/F[\delta])}{\Pr([x]/(F[\delta])^c)} \geq \alpha' \right\}$$

$$BND_{(\alpha', \beta', \delta)}^B(F) = \left\{ x \in U / \beta' < \log \frac{\Pr([x]/F[\delta])}{\Pr([x]/(F[\delta])^c)} < \alpha' \right\}$$

$$NEG_{(\alpha', \beta', \delta)}^B(F) = \left\{ x \in U / \log \frac{\Pr([x]/F[\delta])}{\Pr([x]/(F[\delta])^c)} \leq \beta' \right\}$$

where $\alpha' = \log \frac{\Pr(C^c)}{\Pr(C)} + \log \frac{\alpha}{1-\alpha}$

and $\beta' = \log \frac{\Pr(C^c)}{\Pr(C)} + \log \frac{\beta}{1-\beta}$

5. Rough Indices

Let U be the universe of discourse and α be any value in $(0,1)$. Let $X = \{W_1, W_2, \dots, W_n\}$ be any partition defined on U . For any fuzzy set A define $A[\alpha] = \{x \in U / \mu_A(x) > \alpha\}$ where α is chosen from R -domain satisfying the property that $\text{dil}^n(\alpha)$ and $\text{con}^n(\alpha)$ are the members of R -Domain for any positive integer n [dil represents dilation and con represents concentration]. The lower and upper approximations A_{α} and A^{α} are given by $A_{\alpha} = (A[\alpha])_{\sim}$ and $A^{\alpha} = (A[\alpha])^{\sim}$ respectively [1].

The following algorithm as in [2] illustrates the method of indexing the elements of U , by using the lower and upper approximations of the given fuzzy set A

Let M denote the largest number under consideration such that $n+M$ is always positive and $n-M$ is always negative for any integer n .

5.1 Algorithms

Algorithm rough index (x, A, α)

//Algorithm to obtain rough index of x an element of universe of discourse

//Algorithm returns the rough index

1. Let x_index be an integer initialized to 0
2. Pick the equivalence class K containing x .

If $\mu_A(y) = 0$ for all $y \in K$

begin

$x_index = -M$

goto 6

end

end

3. If $\mu_A(x) = 1$

begin

If $\mu_A(y) = 1$ for all $y \in K$

begin

$x_index = M$

goto 6

end

end

4. compute A_{α} and A^{α}

5. If $x \in A_{\alpha}$

begin

$x_index = M$

while ($x \in A_{\alpha}$)

begin

$\alpha = \text{dil}(\alpha)$ //dilation of α

$x_index = x_index + 1$

compute A_{α}

end

end

else

if $x \notin A^{\alpha}$

begin

$x_index = -M$

while ($x \notin A^{\alpha}$)

begin

$\alpha = \text{con}(\alpha)$ //concentration of α

$x_index = x_index - 1$

compute A^{α}

end

end

else

Let $\beta = \alpha$

compute A^{β}

while ($x \notin A_{\alpha}$ and $x \in A^{\beta}$)

begin

$\alpha = \text{con}(\alpha)$ // concentration of α

$\beta = \text{dil}(\beta)$ // dilation of β

compute A_{α}, A^{β}

$x_index = x_index + 1$

end

if $x \in A_{\alpha}$ then

$x_index = -x_index$

end

6. return x_index

Consider the universe of discourse $U=\{a,b,c,d,e,f,g,h\}$ with the partition $X=\{\{a,e,f\},\{b,g\},\{c,h\},\{d\}\}$. Let $\alpha=0.5$.

Consider the fuzzy set $\{(a,0.6),(b,0.4), (c,0.8), (d,0.24), (e,0.44), (f,0.56), (g,0.98), (h,0.77)\}$. By the above algorithm, 'b' can be indexed by -1 and d can be indexed by $-2-M$. Similarly, other values of U can be indexed. These indices are called rough indices.

Sometimes, the elements of different equivalence classes may have same rough index but in the above it is to be noted that the elements of same equivalence classes have the same rough indices. Clearly, it depends upon the choice of α and the fuzzy set taken under consideration. But,, it is obvious that the elements of the same equivalence classes will have the same rough indices and therefore, instead of indexing the elements of U, one may follow the given algorithm for rough indexing the equivalence classes. Now, this algorithm shall be modify for three way approach on rough sets as follows:

Algorithm Three_Way_rough index (x,A,δ)
 //Algorithm returns the Three_Way_rough index of x

1. Let x_index be an integer initialized to 0
2. Pick the equivalence class K containing x.

If $\mu_A(y)=0$ for all $y \in K$

```
begin
x_index=-M
goto 6
```

end

end

3. If $\mu_A(x)=1$

If $\mu_A(y)=1$ for all $y \in K$

```
begin
x_index=M
goto 6
```

end

end

4. compute $POS_\delta(A)$, $BND_\delta(A)$ and $NEG_\delta(A)$

5. If $x \in POS_\delta(A)$

```
begin
x_index=M
while ( $x \in POS_\delta(A)$ )
begin
     $\alpha=dil(\delta)$  //dilation of  $\delta$ 
     $x\_index=x\_index+1$ 
    compute $POS_\delta(A)$ 
end
end
else
```

```
if  $x \in NEG_\delta(A)$ 
begin
x_index=-M
```

```
while ( $x \in NEG_\delta(A)$ )
begin
```

```
 $\delta=con(\delta)$  //concentration of  $\delta$ 
 $x\_index=x\_index-1$ 
```

```
    compute $NEG_\delta(A)$ 
```

end

end

else

Let $\gamma=\delta$

compute $NEG_\gamma(A)$

while ($x \notin (POS_\delta(A) \cup NEG_\gamma(A))$)

begin

$\delta=con(\delta)$ // concentration of δ

$\gamma=dil(\gamma)$ // dilation of γ

compute $POS_\delta(A) \cup NEG_\gamma(A)$

$x_index=x_index+1$

end

if $x \in POS_\delta(A)$ then

$x_index= - x_index$

end

6. return x_index

This algorithm can be illustrated in the same manner as mentioned in the previous example. Now, we parameterize the algorithm using parameters α and β .

Algorithm Naïve Bayesian_rough index $(x,A,\alpha,\beta,\delta)$
 //Algorithm returns Naïve Bayesian_rough index of x

1. Let x_index be an integer initialized to 0
2. Pick the equivalence class K containing x.

If $\mu_A(y)=0$ for all $y \in K$

```
begin
x_index=-M
goto 6
```

end

end

3. If $\mu_A(x)=1$

begin

If $\mu_A(y)=1$ for all $y \in K$

begin

$x_index=M$

goto 6

end

end

4. compute $POS_{(\alpha,\beta,\delta)}^B(A)$, $BND_{(\alpha,\beta,\delta)}^B(A)$ and $NEG_{(\alpha,\beta,\delta)}^B(A)$

5. If $x \in POS_{(\alpha,\beta,\delta)}^B(A)$

```
begin
x_index=M
while ( $x \in POS_{(\alpha,\beta,\delta)}^B(A)$ )
begin
     $\alpha=dil(\delta)$  //dilation of  $\delta$ 
     $x\_index=x\_index+1$ 
    compute $POS_{(\alpha,\beta,\delta)}^B(A)$ 
end
```

end

end

else

if $x \in NEG_{(\alpha,\beta,\delta)}^B(A)$

begin

$x_index=-M$

while ($x \in NEG_{(\alpha,\beta,\delta)}^B(A)$)

begin

$\delta=con(\delta)$ //concentration of δ

$x_index=x_index-1$

compute $NEG_{(\alpha,\beta,\delta)}^B(A)$

end

end

else

Let $\gamma=\delta$

```

compute NEGγ(A)
while
(x ∉ (POSB(α',β',δ)(A) ∪ NEGB(α',β',γ)(A)))
begin
δ = con(δ) // concentration of δ
γ = dil(γ) // dilation of γ
compute
POSB(α',β',δ)(A) ∪ NEGB(α',β',γ)(A)
x_index = x_index + 1
end
if x ∈ POSB(α',β',δ)(A) then
x_index = - x_index
end
6. return x_index
    
```

6. Naïve Bayesian Indexing In Information System With Fuzzy Decision Attribute

According to the perspective of Z.Pawlak, any information system is given by $T=(U, A, C, D)$, where U is the universe of discourse, A is a set of primitive attributes, C and D are the subsets of A called condition and decision features respectively [C and D may not exist in a few of the information systems].

Consider an information system with conditional attributes $C=\{a_1, a_2, \dots, a_n\}$ and decision attributes $\{d_1, d_2, \dots, d_s\}$ with the records $U=\{x_1, x_2, \dots, x_m\}$. For any index key 'a' in C , the indiscernibility relation is given by $x_i \approx_{a_k} x_j$ (read as x_i is related to x_j with respect to a_k) if and only if $a_k(x_i)=a_k(x_j)$. Clearly, this indiscernibility relation partitions the universe of discourse U . However, the procedure of selecting the appropriate minimal attributes [reducts] for effectiveness is not discussed in this paper.

For example, consider the decision table with $C=\{a,b,c,d\}$ and $D=\{E\}$.

	a	b	c	d	E
x_1	1	0	2	1	1
x_2	1	0	2	0	1
x_3	1	2	0	0	2
x_4	1	2	2	1	0
x_5	2	1	0	0	2
x_6	2	1	1	0	2
x_7	2	1	2	1	1

Let us consider the index key as 'c'. As x_1, x_2, x_4, x_7 have the values 2; x_3, x_5 have the values 0 and x_6 has the value 1. Hence, the partition on U with respect to c can be defined as $\{\{x_1, x_2, x_4, x_7\}, \{x_3, x_5\}, \{x_6\}\}$.

However, in real time systems we can find several information systems with fuzzy decision attributes and hence the scope of the algorithms discussed above would be applicable for such information systems. Here, the Naïve Bayesian rough indexing of the data can be derived from the fuzzy decision attribute as discussed in the previous section.

For example, consider knowledge representation of the information system with $C=\{a,b,c,d\}$ and $D=\{E\}$ where E is of fuzzy natured.

	a	b	c	d	$\mu_E(x_i)$
x_1	1	0	2	1	0.45
x_2	1	0	2	0	0.7
x_3	1	2	0	0	0.65
x_4	1	2	2	1	0.1
x_5	2	1	0	0	0.91
x_6	2	1	1	0	0.6
x_7	2	1	2	1	0.35

On considering 'c' as the index key, the partition obtained is $\{\{x_1, x_2, x_4, x_7\}, \{x_3, x_5\}, \{x_6\}\}$. Let $\delta=0.5$. Here, $E[\delta]=\{x_2, x_3, x_5, x_6\}$. For a given α and β , the Naïve Bayesian indexing algorithm would be implemented further.

7. Conclusion

In this paper, by using the concept of Naïve Bayesian rough sets the approach of indexing the records of the information system is dealt. These rough indices are useful to analyze and index a database when the fuzzy information about the entire key values is obtained.

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