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Performance of FPGA for Home Automation using VHDL

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Abstract: Technology advancements have made the implementation of embedded systems within home appliances. This increased the capabilities and features. There is demand for smart home automation through mobile phones. Bluetooth or GSM modules are cost effective and flexible so it is one of the best choices for smart home automation. This paper presents a novel technology where the user controls the devices through mobiles. Implementation is done using FPGA (Field Programmable Gate Array) as a controller to which the devices are directly interfaced. This paper presents a possible solution whereby the user controls devices by employing a central Field Programmable Gate Array (FPGA) controller to which the devices and sensors are interfaced. Control is communicated to the FPGA from a mobile phone through its GSM interface. This results in a simple, cost effective, and flexible system, making it a good candidate for future smart home solutions.

Keywords: FPGA, UART, GSM, Zigbee.

1. Introduction

The requirement for a suitable technology that enhances the quality of life in homes has always been at the center of research. User needs that a home must satisfy and can vary from basic requirements to external and internal aesthetics to comfort within the home. With the advancements in technology, electrical appliances are filling the homes, providing more comfort to the dwellers and improved entertainment systems. However, their proliferation and costs related to electricity consumption are increasing user demands for home automation systems. Yet, commercially available solutions are still limited and most of the time they are tailor-made for a customer, resulting in high costs. This paper presents a cost-effective solution that uses a Field Programmable Gate Array (FPGA) controller at the core of the system to provide the intelligence for the home system. Moreover, the controller interfaces to a mobile device through the Bluetooth [1] communications port to allow monitoring, configuration, and switching of devices. This allows the user to set the home environment according to the personal needs. This paper is organized as follows; Section II gives some background on systems found in literature. Section III provides an overview of the system developed, while Section IV presents the implementation of a prototype. Section V gives the obtained test results, while a final conclusion is drawn in Section VI.

2. Background Work

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The concept of intelligent homes has attracted the attention of a number of researchers and practitioners during the last years. Most of these recent techniques focus on exploiting wireless communications to communicate with the devices. In [2] the authors introduce the idea of using Bluetooth as a cable replacement for home automation. However, no implementation details are given. An automation system based on Bluetooth was developed in [3]. It consists of a remote and a mobile host controller that communicates with several devices representing the home appliances. A similar

solution was presented in [4], where a Bluetooth multihop mesh topology was used to relay sensor node information to a mobile phone or a personal computer. A Zigbee based home automation system was integrated with a Wi-Fi network through a gateway in [5]. The gateway provides the user interface and accessibility to the system. The system was evaluated using four devices. A similar approach was taken by the authors in [6], where the design of an architecture integrating a Zigbee home network into the Open Service Gateway initiative (OSGi) framework-based home gateway is presented. Techniques that use Internet as the means for home automation have also been proposed. A system based on an embedded controller which is interfaced via an RS232 port to a personal computer web server was presented in [7]. The controller is then connected to the appliances and sensors. The Internet access allows both local and remote access to the home system. A system using the Global System for Mobile communications (GSM), Internet, and speech recognition, was proposed in [8] for real-time monitoring and remote control of the home appliances. This adds flexibility to the system; however, it increases the cost when using GSM technology. The authors in [9] try to improve the Graphical User Interface (GUI) of the home automation system by introducing a 3D visual interface. The aim is to enhance the user experience and allow faster take up of such technologies. This system also exploits Internet to allow dwellers to control and monitor the home from outside.

3. System Design

A block diagram of the system developed is shown in Figure 1. It consists of a mobile phone having a Bluetooth or GSM interface, a central FPGA controller that communicates via the RS-232 protocol to the Bluetooth or GSM interface, and a number of devices which are connected to the central controller. The latter links can be either wired or wireless.

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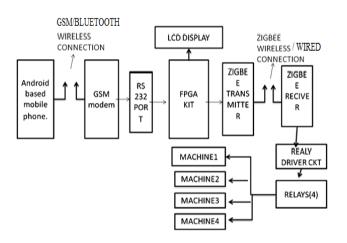


Figure 1. Block diagram of the system

A. Bluetooth or GSM Interface

The central FPGA controller communicates with the Bluetooth or GSM module through a serial interface. This requires that Universal Asynchronous Receiver/Transmitter (UART) is employed on the FPGA. This technology was selected over other solutions because it is available in most mobile phones, it can be implemented with low cost, it consumes low power, and provides a level of security through its use in short or long distances and through its pairing function. The mobile communicates to its inbuilt Bluetooth or GSM module through an Application Programming Interface (API) simplifying the design. On the other hand, a Bluetooth or GSM module must be interfaced with the FPGA, where accurate clocking must be generated for the UART to correctly interpret the received data.

B. Mobile Device

The system requires a mobile device or a Smartphone having a Bluetooth or GSM interface. The application running on the device must present a simple, yet user-friendly, graphical user interface to aid the user in performing the correct commands and settings, and understanding the monitored values coming from the sensors. The software developed needs to use a portable platform that is compatible with devices coming from different manufacturers. Java was used in this work.

C. Control and Monitoring Devices

Paper ID: 020141253

The number of control and monitoring devices attached to the FPGA depend on the number of free input/output ports available on the FPGA. Furthermore, the system can be further expanded by cascading FPGAs or by multiplexing data coming from different sensors. This makes the system scalable. The devices connected to the FPGA can use either a wired connection or a wireless one, such as Zigbee or Infrared. In this work wired solutions were used, however, the interface can be easily replaced by a wireless solution. The modules interfaced were; a temperature sensor, a motion sensor, a light sensor, a relay switch, a Light Emitting Diode (LED) and a servo. These represent typical sensors used in the home which can allow the central controller to make decisions on whether to switch on or off various devices. Moreover, the circuits tested emulate low voltage switching, high voltage control via the relay, and motor control through the servo. The latter is useful for example to control light in a room by opening or closing shutters. Thus, the system covers most of the typical interfaces found in appliances in homes.

4. Implementation

The central controller was implemented on a Basys2 development board [10], which uses a Xilinx Spartan-3E FPGA [11]. The hardware inside the FPGA was developed using the Very High Speed Integrated Circuit (VHSIC) Hardware Description Language (VHDL). A modular approach was taken such that the design and test phases are simplified and scalability is facilitated. Most of the modules were developed using Finite State Machines (FSM). The UART required for the Bluetooth or GSM interface was developed using a transmit unit and a receive unit. The transmit unit consists of the Tx module which does the transmission, the Data to Send module that passes the data to be sent to the Tx, and the clock divider module which determines the baud rate. The state machine for the Tx module is shown in Figure 2. The Tx module starts in the Wait for Data state where it waits for the data to become available in the Data to send module. Once data is present, the enable bit is set and the state moves to send. At this point data is transmitted starting from the Least Significant Bit (LSB). Eight bits of data are sent at the selected baud rate encapsulated between a start and a stop bit. When this frame is sent, the state goes back to Wait for Data to get the second frame which completes the packet to be transmitted. When the two bytes of data are sent the state goes to RST to reset the registers and send an acknowledge signal to the Data to Send module. The enable bit is then cleared and the process starts again in the Wait for Data state. The Data to send module is responsible for acknowledgments that are sent to the mobile device to confirm that a command has been executed, relay sensor readings, and transmit the appliances' status report. The module is initialized in the Waiting state where it listens for data coming from the Algorithm module. Once data is sensed, the state moves to send which sets the enable out bit to inform the Tx unit. When the Tx unit acknowledges the data, the state moves to RST where the Algorithm module is informed that the data has been sent. This module responds by setting the default choice to "0000" effectively resetting the state to Waiting. The module also receives data from the Temperature module which interfaces with the temperature sensor. The process is the same with the exception that the temperature reading is loaded in the registers instead of the acknowledgment.

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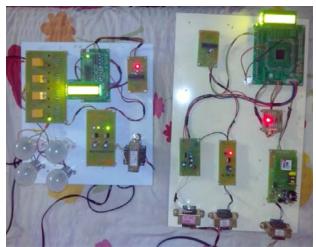


Figure 1: Hardware Implementation

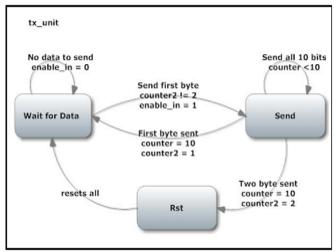


Figure 2: The Tx Finite State Machine

5. Observation

VHDL test benches were designed to test all the developed VHDL code both at block level and at top level before downloading the synthesized code on the FPGA. The waveforms were checked to verify correct operation, both states and timings, of the hardware. The devices connected to the FPGA were also tested by forcing outputs and inputs and checking the functionality. All interfaced circuits functioned as expected. The communications channel had to be tested as well. A serial port monitoring program installed on a PC was used for this. A Bluetooth or GSM dongle was connected to the PC and the communication between mobile phone and the PC, and the PC and the FPGA controller were tested. This was done by sending Bluetooth or GSM commands and monitoring the replies. Once the controller and the Bluetooth or GSM connection were tested, the whole system was tested exhaustively by sending commands and reading and noting the results.

6. Conclusion

An implementation of a home automation system using an FPGA central controller was presented. The FPGA was selected as, compared to microcontrollers, it provides a larger number of input/output ports and the parallel

implementation of hardware results in faster algorithm execution. The user interface on the mobile phone communicates with the FPGA using the Bluetooth or GSM interface. This leads to a low cost system that can be easily scaled up. Furthermore, pairing allows some level of security to avoid network intrusion.

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