

# Traffic Light Control Using Accelerometer Sensor on ARM Platform

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**Abstract:** *This paper is to build a system in which the signaling time at traffic signaling junction will be controlled according to the availability of ambulances or VIP vehicles. In this paper, "Traffic control System" is based on the traffic rules. For that traffic police gestures are important. There are two methods for gesture recognition, first is vision based and other is sensor based. In this paper sensor based method is used for gesture recognition on ARM platform. For that thresholding method is used as detecting algorithms. SD card is used to store the voice data and transmitted using XBEE module.*

**Keywords:** MEMS, Microcontroller, ZIGBEE and LCD.

## 1. Introduction

When traffic is very heavy, an automatic traffic light system is not efficient to control traffic, causing traffic jam. In this case, it is necessary to switch off the traffic light and let traffic police guide traffic by gestures. In the case of bad weather or obstruction by other vehicles, however, sometimes it is difficult for all drivers to recognize the gestures. It would be useful if the traffic light can follow the traffic police gestures. Two methods are considered suitable for gesture recognition. The first one is to use vision sensors like cameras to acquire images, which are analyzed to recognize the gestures. The second one is to place inertial sensor on the traffic police hand and extract the motion characters. The most advantage of the vision method is that it can recognize gestures without adding any extra hindrance to the police. However, it suffers from poor illumination, e.g. at night or in fog weather.

Due to the advantages of low cost and small size, MEMS accelerometers have been used widely in gesture recognition. By fixing two 3-axis accelerometers on wrist of both hands, so the arm movement and hand position, when the arm is steady, can be extracted. By recognizing traffic police gestures and synchronizing the traffic lights with them, it is envisaged that this application will give help to vehicle drivers. There are no systems for regulating the traffic given as following: The author Zhang Yuye et al. [11] System use AT89C51 and CAN BUS controller which leads to complicated design and cost of the system more because of CAN BUS controller. Also power requirement will be more in case of AT89C51. The author Manoj Kanta Mainali et al. [7] proposed a genetic algorithm approach to estimate the traffic volume in road sections without the traffic information of road sections. This method can estimate the unknown traffic volume using only the known traffic volumes. The author Cai Bai-gen et al. [3] design a vehicle detection system based on magneto-resistive sensor composed by wireless traffic information collection nodes which are set on two sides of road to detect vehicle signal. The magneto-resistive sensor is costly and maintenance cost of the system will be more if the system fails. This system is lack of emergency measures.

The author S.L.Toral et al. [13] design will provide good result for vehicle detection where ARM-based video processor not only deals with the video processing algorithms but again the cost of system design will be more because camera will be required to capture video. The author Shilpa S. Chavan et al. [12] design of traffic light controller handles major problem of conventional traffic signal. At certain junction, sometimes even if there is no traffic but people have to wait because the traffic light remains red for the preset time and road users wait until the light turn to green. They try to solve this problem effectively by using Microcontroller (89c51), GSM but system will lead to complications.

The author Ahmed S. Salama et al. [8] provide integrated intelligent traffic light system using photoelectric sensors distributed on long range before and after traffic light on roads. Emergency cases such as, the passing president car and ambulance that require immediate opening of traffic signal. The system has the ability to open a complete path for such emergency cases until reaching the target but this system does not operate well when more than one emergency vehicle come on the signal from two sides. The author Dinesh Rotake, Swapnil Karmore et al. [2] provides ITSC system. When more than one emergency car came then most of the system fails. The ITSC system consist of AVR-32 microcontroller with inbuilt 8-channel ADC to receive IR-input from IR-transmitter which is embedded in the emergency vehicle. The 8-IR sensors are used to detect the emergency vehicle and open the divider gate to pass emergency car and then immediately closed the gate.

## 2. System Design Model

The proposed system implementation, the traffic police hand gestures are important. So that requires suitable hand gesture recognition technique. There are no "Hand Gesture Recognition techniques" present, from that only two techniques are considered first is vision based and second sensor based. In vision based system for traffic control then it requires camera, time consuming technique and have some disadvantages. So that to design realtime traffic control system, here used sensor based technique. In this system, accelerometer sensor is used for hand gesture recognition. Block diagram of proposed system is given in fig.no.1. Here

utilize a sensor on handheld unit which integrated a tri-axes accelerometer chip as a handheld input device in this interaction system. When the human performs a gesture, the sensor will collect the data flow output by accelerometer chip, and send it to PC via wireless protocol. Here consider this raw data stream fetched from sensor as an “input pattern”.

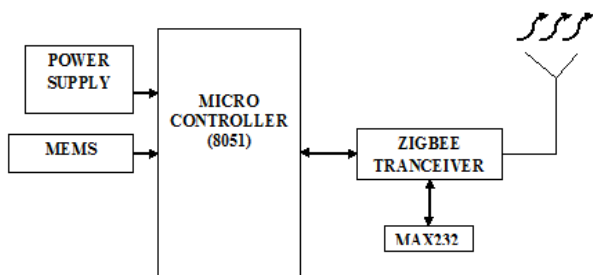


Figure 1: transmitting section

According to the daily experience, the patterns generated by the movement of hand when human performing the same gestures satisfy certain statistical rules to some extent, based on it we propose the “standard pattern”. The “standard pattern” is a class of pre-defined patterns, each one corresponding to a special “input semantics”. When user performed a gesture, the sensor will send the “input pattern” to interaction system, then system will find out the most approximate “standard pattern”, this also can be regarded as a procedure of recognition, and finally the interaction system get an input semantic according to the recognition result.

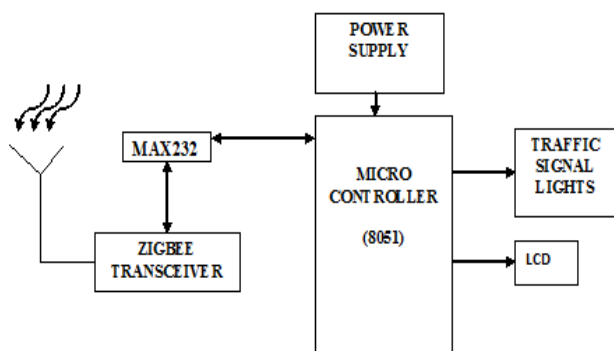


Figure 2: monitoring section

The three axis accelerometer are basically used to identify the movements across the three axis i.e. x-axis, y-axis, z-axis. Accelerometer is an electronic device which is interfaced using I2C protocol and provides the reading after every 1msec. According to the requirement of the application, the microcontroller will take the reading from the accelerometer within a fixed interval of time and do the necessary operation according to the requirement of the application.

It is possible to create the source files in a text editor such as Notepad, run the Compiler on each C source file, specifying a list of controls, run the Assembler on each Assembler source file, specifying another list of controls, run either the Library Manager or Linker (again specifying a list of controls) and finally running the Object-HEX Converter to convert the Linker output file to an Intel Hex File. Once that has been completed the Hex File can be downloaded to the

target hardware and debugged. Alternatively KEIL can be used to create source files; automatically compile, link and convert using options set with an easy to use user interface and finally simulate or perform debugging on the hardware with access to C variables and memory. Unless you have to use the tools on the command line, the choice is clear. KEIL Greatly simplifies the process of creating and testing an embedded application. The user of KEIL centers on “projects”. A project is a list of all the source files required to build a single application, all the tool options which specify exactly how to build the application, and – if required – how the application should be simulated. A project contains enough information to take a set of source files and generate exactly the binary code required for the application. Because of the high degree of flexibility required from the tools, there are many options that can be set to configure the tools to operate in a specific manner. It would be tedious to have to set these options up every time the application is being built; therefore they are stored in a project file. Loading the project file into KEIL informs KEIL which source files are required, where they are, and how to configure the tools in the correct way. KEIL can then execute each tool with the correct options. It is also possible to create new projects in KEIL. Source files are added to the project and the tool options are set as required. The project can then be saved to preserve the settings. The project is reloaded and the simulator or debugger started, all the desired windows are opened. KEIL project files have the extension

### 3. Experimental Results

Here two unit are present, first is base unit and another is handheld unit. At the start of system, initializing of all component. There are two mode of the system first is auto mode second is manual mode. The results are categorized based on objective and mode of the system. 1) To recognize real time hand gesture using accelerometers sensor. 2) To control hardware according to hand gesture. First system in auto mode, so that at base unit traffic light signal are glowing automatically according to the programmed them. If there is need to control the traffic by traffic police gesture, then system change the mode i.e. it switch to manual mode by pressing manual mode button. The system is controlled by hand gesture of traffic police. One example is given below.

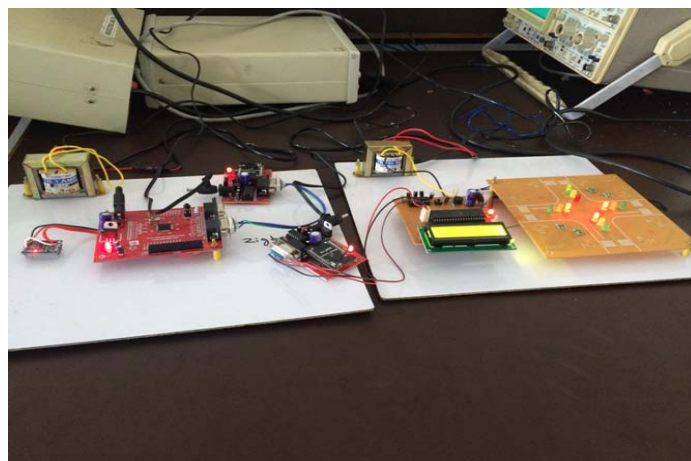


Figure 3: Experimental kit

According to this project, it employs 2 sections; one is placed at traffic signal junction and the other one section Ambulance section. The section placed in the ambulance contains a MEMS accelerometer for the operations Emergency, Normal, out, direction 1 and direction 2. So according to this project, whenever the ambulance is yet to reach a traffic signal junction, the concerned person need to press the switches like Emergency / Normal and direction 1 / 2 informing the direction and ambulance reaching the signal junction. The other section placed at traffic signal receives the information and takes the control action. The control action is in the form of timing for Green lights. The communication between the sections is done using Zigbee technology. Each and every section is designed around a microcontroller as a control unit. The Zigbee module is interfaced to microcontroller.



Figure 6: CASE 3

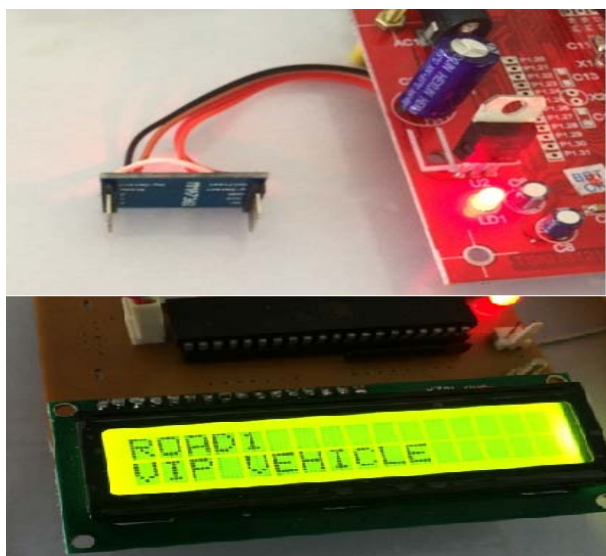


Figure 4: CASE 1



Figure 7: CASE 4

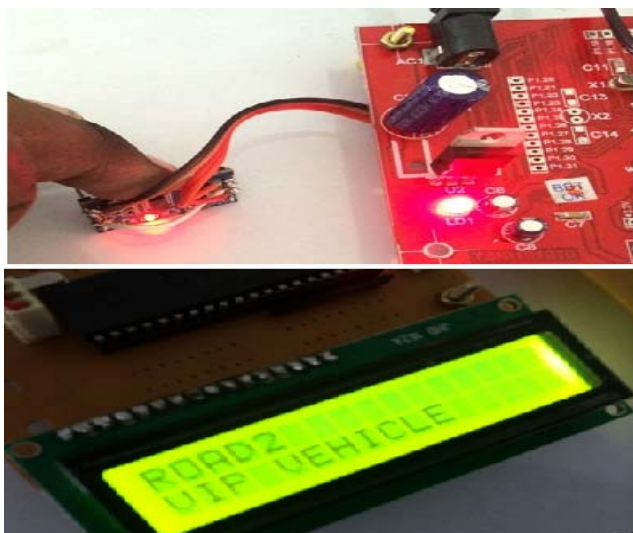


Figure 5: CASE 2

#### 4. Conclusion

The design system is implemented using accelerometer sensor-based hand gesture recognition technique. This is user friendly system, where the complex human-computer interface is required. The system is more accurate than vision based system as an illumination problem is solved.

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