

Fast Speed Base of Two Multiplication

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Abstract: *Multiplication is major concern in calculations. Performing multiplication on floating-point data is a long course of action and requires huge quantity of processing tremendous amount of handling time. By improve the fast speed of multiplication task overall speed of the system can be enhanced. The Bottleneck in the floating-point multiplication process is the multiplication of mantissas which need 53×53 bit integer multiplier for double precision floating-point numbers and Medic, and Chronic Signed digit algorithms exists to compare parameters like speed, complexity of routing, pipe lining, resource required on FPGA. The comparison showed that Chronic Signed Digit Algorithm and Booth Multiplication Algorithm is better than Medic algorithm concerning speed and resources required on spartan3 FPGA*

Keywords: Binary Multiplier Booth Multiplication Algorithm.

1. Introduction

Booth Multiplication Algorithm One of the solutions for realizing high-speed multipliers is to enhance parallelism which help in decreasing The number of subsequent calculation stages. The original version of Booth's multiplier (Radix — 2) had two disadvantages. The number of add / subtract operations become variable and hence they became inconvenient while designing Parallel multipliers. Algorithm becomes inefficient when there are isolated 1s. These problems is overcome by using Radix 4 Booth's algorithm which can scan strings of three bits with the algorithm given below. The design of booth multiplier in this work consist of four modified booths encoder four sign 17 expansion corrector four fractional item generator (Comprise 5: 1 multiplexer) and finally booth multiplier techniques (Meier-et al.1996) increase speed by reducing the number of partial product by half. An 8-bit booth multiplier needs only four partial products to be added instead of eight partial products generated using the conventional multiplier.

2. Low Power Technique for Multiplier

The majority of real life applications, such as microprocessors, and digital processing implementation, require the computation of multiplier operation. Specifically speed area and power efficient therefore of a multiplier is a very challenging problem. Some existing techniques for low power multiplier that reduce the dynamic power consumption by minimizing the switched capacitance are discussed one by one in the following paragraphs. In general, there are sequential and combination multiplier implementations. In this, multiplication consists of Partial Products 11 Generation Partial Product Reduction and finally Carry Propagate Addition. Here a combination case is considered because the scale of integration now is large enough to accept parallel multiplier implementations in digital VLSI systems. A different multiplication algorithm vary in the approaches of PPG, PPR, and CPA. For PPG, radix-2 is the easiest. To reduce the number of Partial Products and consequently reduce the area/delay of PP reduction, one operand is usually recoded into high-radix digit sets. The most well known one is the radix-4 digit set $\{-2, -1, 0, 1, 2\}$. For PPR, two decisions

exist: decline by the sections, performed by an assortment of adders performed by a variety of adders; and decrease by the segments, performed by an assortment of counters.

The last CPA requires a quick viper plot since it is on the basic way. In some cases, final CPA is postponed if it is advantageous to keep redundant results from PPG for further arithmetic operations.

3. Booth Multiplication Algorithm

In BOOTH multiplication algorithm to reduce the time needed for multiplication number of partial products to be added are reduced [1-3]. BOOTH recording reduces the number of adder units needed and hence reduced the delay by reducing number of nonzero bits in the multiplier [2]. In BOOTH recoding, the long sequence of 1s is replaced by two no zero bits; for example, If digits j through (down to) k are 1s, then, $2^j + 2^{j+1} + \dots + 2^{k+1} + 2^k = 2^{j+1} - 2^k$ This represents, the sequence of additions can be replaced by an addition of the multiplicand shifted by $j+1$ positions and a subtraction of the multiplicand shifted by k positions [5]. The drawback of BOOTH recording is the high power consumption and thus reduced efficiency [3-8].

4. Literature Review

This Chapter presents a brief introduction of design methods that explore the need for "true power minimization"; the need for working in a large dimension search space, where power, and performance of different solutions are compared. These include system level architecture optimization (external loop), block level optimization (intermediate loop), and fixed topology optimization (inner loop). Given that the inner-loop optimization deal with continuous variables, one need some way to guide the optimization to yield optimal solutions globally. The key is to use the energy-delay trade-off for many optimizations together.

Call away et al (1996) reported a number of studies on transition activity reduction in digital multiplier and demonstrated quantitatively that switching activity with in just the partial product reduction, equipment would be

significantly better for the tree structure over the exhibit. The fast multiplier, based on a rather regular structure called a multiplier based on a redundant binary adder tree, has been proposed by Tankage (2000). In it, multiplicand-products are created first as in other equal multipliers, being viewed as excess double numbers, and are summarized pair-wise by methods for repetitive twofold adders associated in the parallel tree structure. At that point at last the item spoke to in the excess paired portrayal is changed over into the standard parallel portrayal. The excess twofold portrayal, likewise called the paired marked digit portrayal is a binary representation with a digit set $\{-1, 0, 1\}$. Further, the subtraction of binary number also is derived by replacing every 1 by 0 and -1 by 1 in the redundant binary number, from the binary number that is derived by replacing 1 by 0. A fixed-point multiplication involves two basic steps: generating Partial Products (PPs) and accumulating the generated PPs. The diverse multiplication schemes differ in the generation, and/or accumulation methods. Consequently, speed-up in the multiplication process is achieved in two ways: by generating less number of PPs in the first step or by accelerating their accumulation in the second step.

The most straightforward plan for duplication, known as move and-include conspire, comprises of patterns of moving and including with equipment or programming control circles.

Saeed Tahmasbi Oskui et al. 2007 likewise endeavored the PPs which were produced utilizing multiplexers or/and entryways in an unsigned radix-2 shift-and-include increase. For multiplication of signed-magnitude numbers, the unsigned multiplication core can be used for the magnitude part of the inputs, with an extension that the sign bit is computed separately by checking the two input operands' sign bits. Multiplication of signed values with complement representation is a bit more complex. One way is to complement the negative operands, multiply the unsigned values, and then complement the result if necessary, i. e. when only one of the inputs operands is negative.

Such a Complement and post-complement method is suitable for 1's complement numbers but it is too complicated for 2's complement numbers. For a 2's supplement multiplier to yield the right result of its information sources, a sign expansion is required on PPs. 2.2.1 Improvement of Multipliers Operating with Variable Bit Length The depiction of various old style multiplier configuration to clear out the least introduction, and most power hungry structure has furthermore 13 been tried by Law et al (1999). Law et al (1999). They concluded that Wallace Tree multiplier structures provided the optimal solutions for a 0.8μm CMOS technology. The depiction of various old style multiplier configuration to clear out the least introduction, and most power hungry structure has furthermore 13 been tried by 8 bits to 64 bits, so that a total of 192 different structures were evaluated. The optimal configuration from the investigation used the Add/Shift algorithm followed by a Wallace Tree and a Han and Carlson adder, to provide the final addition step in the multiplication process. Interestingly, the authors found the use of solutions which.

Customarily gave great silicon zone arrangements, similar to the Braun multiplier. Be that as it may, it demonstrated very wasteful in term of intensity utilization. This emphasis es again the necessity for making changes in design strategy from the traditional speed-area centric approach to a methodology which attempts to optimize a design using power-speed-area metrics. Indeed the force utilization coming about because of this work gives off an impression of being founded on elevated level boolean models of the multiplier structure and not on definite low level recreation. They may not be sufficiently precise to take into account total certainty.

Choi et al (2000) proposed an idea called Partially Guarded Computation (PGC), divided the arithmetic units, e. g., adders, and multipliers, into two parts, and turned off the unused part to minimize the power consumption. The reported result showed that the PGC can reduce power consumption in an array multiplier but with the area overhead. A new partial product reduction algorithm using counter architecture was designed by Assady (2009). A new high-speed multiplier has been presented. In partial item decrease stage another tree structure has been changed and in the last expansion stage another crossover snake utilizing 4-bits blocks 14 has been introduced. In partial product reduction step a new tree structure has been modified and in the final addition step a new hybrid adder using 4-bits blocks 14 has been presented. The proposed booth algorithm has dramatic effect on multiplier performance. The modified algorithm and structure for multiplier usage exploit new snake circuits so as to make a widespread counter that diminishes the basic way of the multiplier.

Benini et al. (2000) proposed a design that incorporated a technique for glitching power minimization by replacing some existing gates. These gates were practically proportionate and could be solidified by declaring a control signal. This technique can be applied to replace layout level descriptions and to guarantee predictable results. Anyway it can accomplish reserve funds of just 6.3% in absolute force dissemination since it works in the format condition which is firmly limited. The epic plan incorporates three methods, in particular Signal Flow Optimization (SFO), Left to Right Leap Frog (LRLF) structure, and upper/lower split structure, to advance the exhibit multipliers, proposed by ercegovic and huang (2006). The SFO and LRLF methods are utilized for signal adjusting of the PPR stage in a multiplier. The upper/lower split structure is utilized to abbreviate the way of the PPR stage to forestall the glitch impact (Henzler et al. 2004). This design can save about 20% power dissipation when compared with conventional right to left multipliers (2.2.2) rs and multipliers.

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